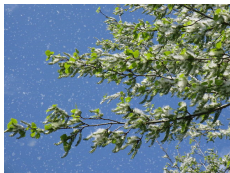


# Lecture II: The evolution of dispersal

January 2017

# Terminology

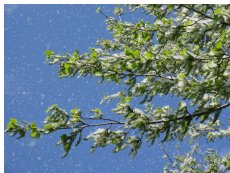
**Dispersal** “Any movement of individuals or propagules with potential consequences for gene flow across space”  
[Ronce, 2007]



(c) Wikimedia

# Terminology

**Dispersal** “Any movement of individuals or propagules with potential consequences for gene flow across space”  
[Ronce, 2007]



(c) Wikimedia

**Migration** “Mass directional movements of large numbers of a species from one location to another.”  
[Begon et al., 1996]

*But in population genetics, often used as a synonym of dispersal.*



(c) Wikimedia

# Why disperse?

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- ▶ Avoid kin competition

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- ▶ Avoid kin competition
- ▶ Avoid inbreeding

## Why disperse?

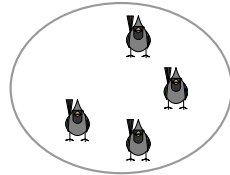
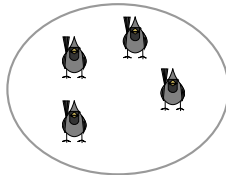
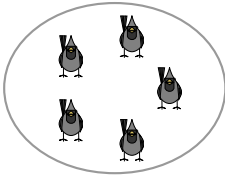
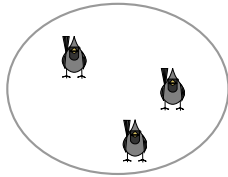
- ▶ Avoid kin competition
- ▶ Avoid inbreeding
- ▶ Explore new territories

## Why disperse?

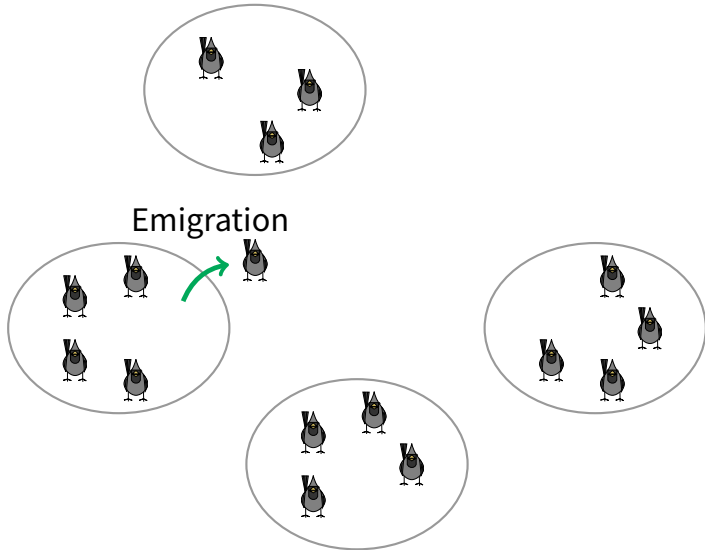
- ▶ Avoid kin competition
- ▶ Avoid inbreeding
- ▶ Explore new territories
- ▶ Find better conditions.



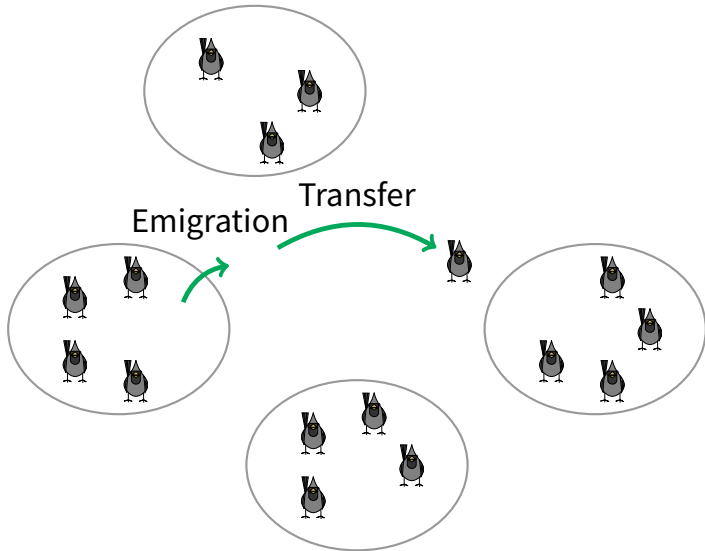
# Dispersal stages



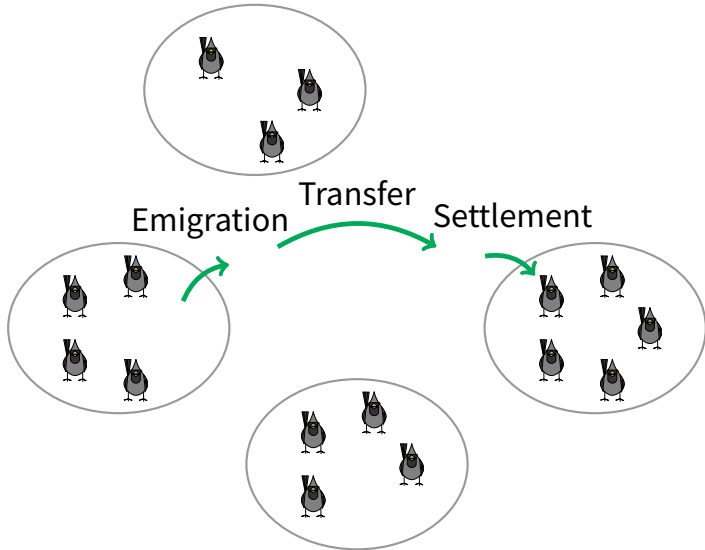
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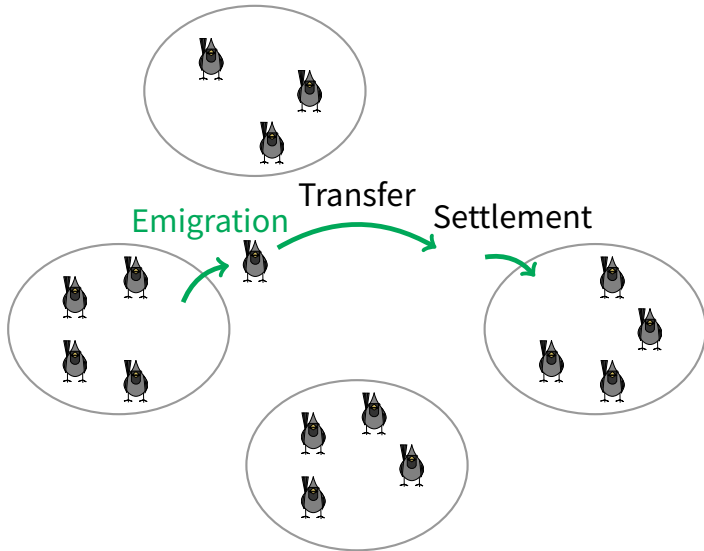
# Dispersal stages



# Dispersal stages



# Dispersal stages



# Outline

Introduction

**Dispersal and kin competition**

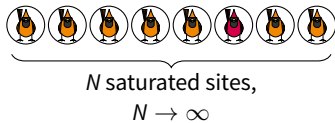
Hamilton & May 1977

Island model

In spatially heterogeneous environments

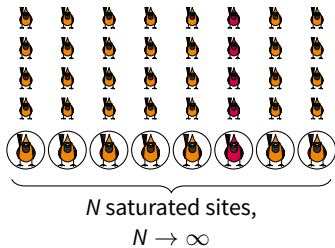
# An iconic example: [Hamilton and May, 1977]

## Model



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## Model

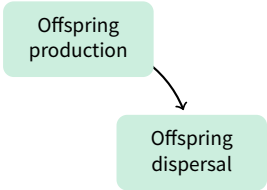
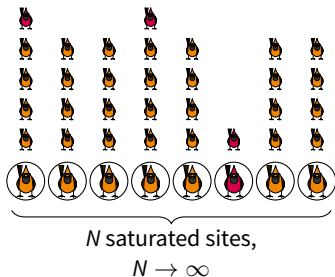


Offspring  
production



# An iconic example: [Hamilton and May, 1977]

## Model

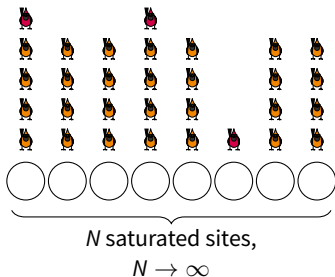


Emigration probabilities:  $x = 0, y > 0$

Cost of emigration  $c = 1 - p$ .

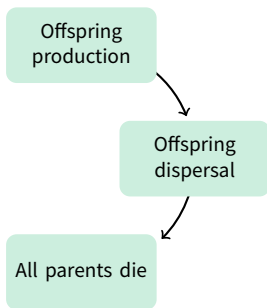
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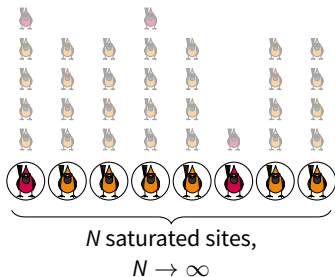
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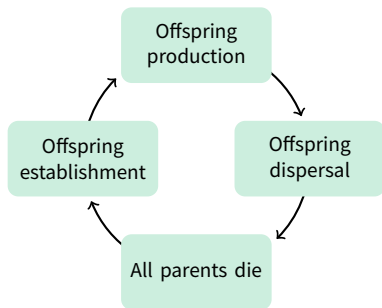
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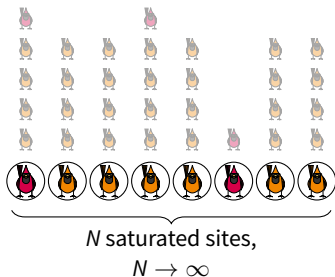
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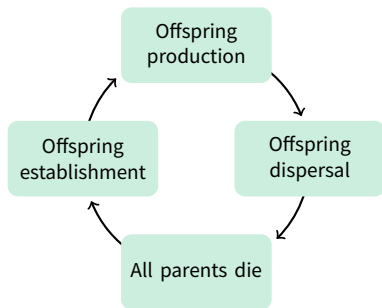
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$$w(y, x) = \frac{1 - y}{1 - y + (1 - c)x} + \frac{(1 - c)y}{1 - x + (1 - c)x}$$

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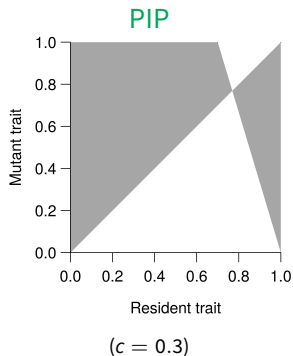
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$$D(x) = \left. \frac{\partial w(y, x)}{\partial y} \right|_{y=x} = \frac{(1 - c)(1 - x(1 + c))}{(1 - cx)^2}$$



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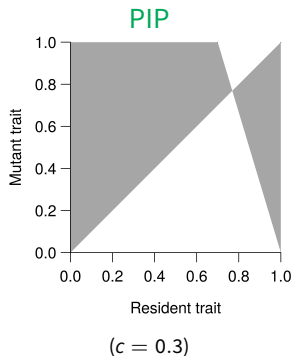
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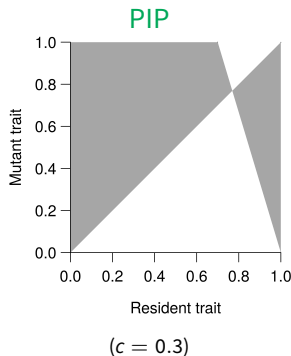
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$$\frac{dD(x)}{dx} = -\frac{(1 - c)(1 - c + (c + 1)cx)}{(1 - cx)^3} \leq 0$$





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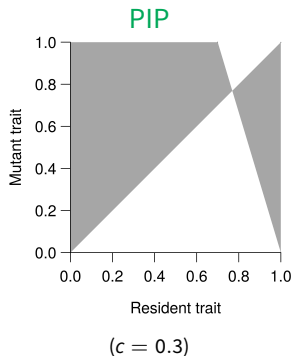
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### ► Convergence stability

$$\frac{dD(x)}{dx} = -\frac{(1-c)(1-c+(c+1)cx)}{(1-cx)^3} \leq 0$$

### ► Uninvadability

$$\left. \frac{\partial^2 w(y, x)}{\partial y^2} \right|_{y=x=x^*} = -2(1-c)(c+1)^2 \leq 0$$



## An iconic example: [Hamilton and May, 1977] (3)

*We acknowledge that this simple model probably has few close parallels in the real world. Nevertheless it may usefully force a re-examination of some widely held ideas about migration.*

[Hamilton and May, 1977]

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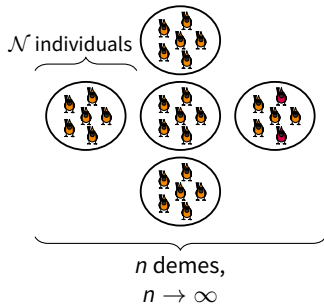
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**Kin competition** Competition between related individuals.

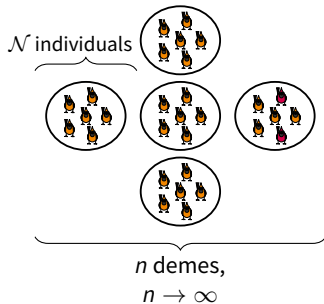


# Dispersal evolution in a subdivided population



- $Z_r$  Emigration probability of residents
- $Z_m$  Emigration probability of mutants
- $c$  Cost of dispersal
- $\mu$  Mutation probability ( $\mu \rightarrow 0$ ).

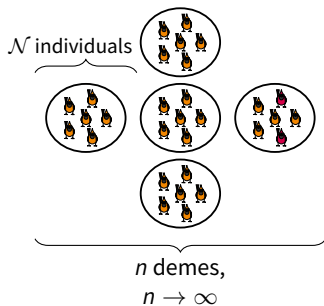
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$q_0(z_m, z_r)$ : Average frequency of mutants in demes that contain mutants.

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## Invasion fitness

$$w(z_m, z_r) = \frac{1 - z_m}{1 - (q_0 z_m + (1 - q_0)z_r) + (1 - c)z_r} + \frac{(1 - c)z_m}{1 - z_r + (1 - c)z_r}$$

[Gandon and Rousset, 1999]

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$$w(z_m, z_r) = \frac{1 - z_m}{1 - (q_0 z_m + (1 - q_0)z_r) + (1 - c)z_r} + \frac{(1 - c)z_m}{1 - z_r + (1 - c)z_r}$$

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$$D(z) = \left. \frac{\partial w(z_m, z_r)}{\partial z_m} \right|_{z_m=z_r=z} = \frac{q - c - z(q - c^2)}{(1 - cz)^2},$$

with  $q = q_0(z, z)$ .



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### Computing $q$ , recursively [▶ More on \$q\$](#)

$$q_{t+1} = \frac{1}{\mathcal{N}} + \frac{\mathcal{N} - 1}{\mathcal{N}} \left( 1 - \frac{(1 - c)z}{1 - cz} \right)^2 q_t$$

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## Dispersal evolution in a subdivided population (3)

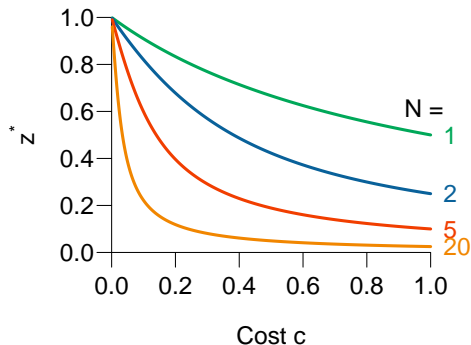
### Singular strategy

$$z^* = \frac{1 + 2c\mathcal{N} - \sqrt{1 + 4c^2(\mathcal{N} - 1)\mathcal{N}}}{2c(1 + c)\mathcal{N}}.$$

## Dispersal evolution in a subdivided population (3)

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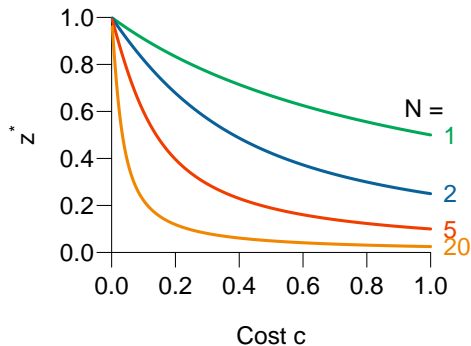
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# Dispersal evolution in a subdivided population (4)

Invadability

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$$\frac{\partial^2 w(z_m, z_r)}{\partial z_m^2} \Big|_{z_m=z_r=z^*} = \frac{2}{(1 - cz^*)^2} \left[ (1 - z^*) \left( \frac{(q^*)^2}{1 - cz^*} + \frac{\partial q_0(z_m, z_r)}{\partial z_m} \Big|_{z_m=z_r=z^*} \right) - q^* \right]$$

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- ▶ In this model, always  $z^*$  is always uninvadable [Ajar, 2003].

## Dispersal evolution in a subdivided population (4)

### Invasibility

$$\frac{\partial^2 w(z_m, z_r)}{\partial z_m^2} \Big|_{z_m=z_r=z^*} = \frac{2}{(1-cz^*)^2} \left[ (1-z^*) \left( \frac{(q^*)^2}{1-cz^*} + \frac{\partial q_0(z_m, z_r)}{\partial z_m} \Big|_{z_m=z_r=z^*} \right) - q^* \right]$$

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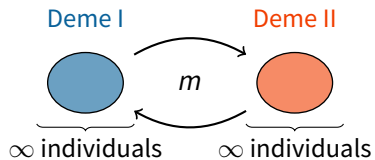
- ▶ In this model, always  $z^*$  is always uninvadable [Ajar, 2003].
- ▶ But with heterogeneity in deme sizes, diversification can occur [Massol et al., 2011]

Introduction

Dispersal and kin competition

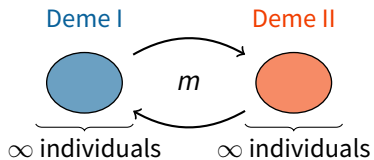
**In spatially heterogeneous environments**

## Another classic: [Balkau and Feldman, 1973]



Life-cycle Selection then dispersal.

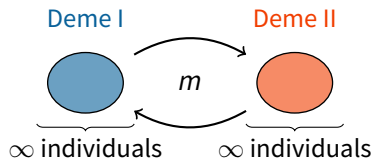
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► Locus A: local adaptation

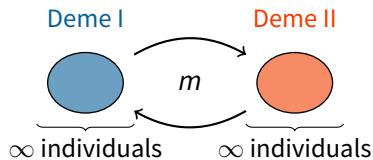
Fitness:

	in I	in II
A	$1 + s$	1
a	1	$1 + s$

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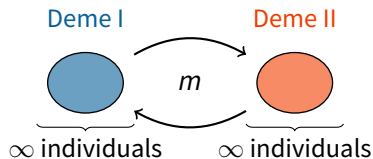
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- ▶ Locus B: emigration

B  $z$   
b  $z_m$ .

## Another classic: [Balkau and Feldman, 1973]



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With AB and aB

Frequency of AB is  $x$  in deme I and  $y$  in deme II.

► Locus A: local adaptation

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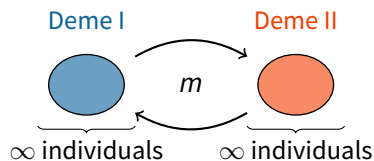
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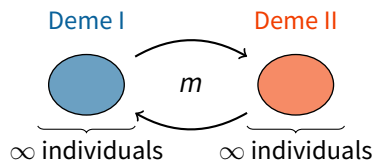
Genotypes AB, Ab, aB, ab.

With AB and aB

Frequency of AB is  $x$  in deme I and  $y$  in deme II.

$$x' = (1 - z) \frac{(1 + s)x}{(1 + s)x + 1 - x} + z \frac{y}{y + (1 + s)(1 - y)}$$
$$y' = z \frac{(1 + s)x}{(1 + s)x + 1 - x} + (1 - z) \frac{y}{y + (1 + s)(1 - y)}.$$

## Another classic: [Balkau and Feldman, 1973]



- ▶ Locus A: local adaptation

Fitness:

	in I	in II
A	$1 + s$	1
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B	$z$
b	$z_m$

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$$y' = z \frac{(1 + s)x}{(1 + s)x + 1 - x} + (1 - z) \frac{y}{y + (1 + s)(1 - y)}.$$

→ Equilibrium  $(\hat{x}, \hat{y}) = (\hat{x}, 1 - \hat{x})$ .

## Another classic: [Balkau and Feldman, 1973] (2)

### Dynamics with the four genotypes

		AB	Ab	aB	ab
Frequencies:	in deme I	$x_1$	$x_2$	$x_3$	$x_4$
	in deme II	$y_1$	$y_2$	$y_3$	$y_4$

## Another classic: [Balkau and Feldman, 1973] (2)

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$$x'_1 = (1 - z) \frac{(1 + s)x_1}{(1 + s)(x_1 + x_2) + (x_3 + x_4)} + z \frac{y_1}{(y_1 + y_2) + (1 + s)(y_3 + y_4)}$$

$$x'_2 = (1 - z_m) \frac{(1 + s)x_2}{(1 + s)(x_1 + x_2) + (x_3 + x_4)} + z_m \frac{y_2}{(y_1 + y_2) + (1 + s)(y_3 + y_4)}$$

$$x'_3 = \dots$$

## Another classic: [Balkau and Feldman, 1973] (2)

### Dynamics with the four genotypes

	AB	Ab	aB	ab
Frequencies: in deme I	$x_1$	$x_2$	$x_3$	$x_4$
in deme II	$y_1$	$y_2$	$y_3$	$y_4$

$$x'_1 = (1 - z) \frac{(1 + s)x_1}{(1 + s)(x_1 + x_2) + (x_3 + x_4)} + z \frac{y_1}{(y_1 + y_2) + (1 + s)(y_3 + y_4)}$$

$$x'_2 = (1 - z_m) \frac{(1 + s)x_2}{(1 + s)(x_1 + x_2) + (x_3 + x_4)} + z_m \frac{y_2}{(y_1 + y_2) + (1 + s)(y_3 + y_4)}$$

$$x'_3 = \dots$$

### Invasion analysis

Local stability of the equilibrium without b,

$$(\hat{x}, 0, 1 - \hat{x}, \hat{y}, 0, 1 - \hat{y}, 0)$$

► More on stability analysis

## Another classic: [Balkau and Feldman, 1973] (3)

ev = Eigenvalues[Jac] // FullSimplify

$$\left\{ \frac{4(1+s)}{(2+s-2z-sz+\sqrt{s^2-2s^2z+(2+s)^2z^2})^2}, -\frac{4(1+s)(-1+2z)}{(2+s-2z-sz+\sqrt{s^2-2s^2z+(2+s)^2z^2})^2}, -\frac{4(1+s)(-1+2z)}{(2+s-2z-sz+\sqrt{s^2-2s^2z+(2+s)^2z^2})^2}, \right.$$

$$1, \left( 4+2\sqrt{s^2-2s^2z+(2+s)^2z^2}+s^2(-1+z)(-1+zm)+4z(-1+zm)-s(4-4z+\sqrt{s^2-2s^2z+(2+s)^2z^2})(-1+zm)- \right.$$

$$2\left( 2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)zm-\sqrt{2}\sqrt{\left( \left( s^2(-1+z)^2+2\left( 1+2z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)z^2-z\left( 2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right) \right) + \right.$$

$$\left. \left. s\left( 2+4z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)z^2-z\left( 4+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right) \right) \left( s^2-2s^2zm+(2+s)^2zm^2 \right) \right) \Big/$$

$$\left( 2+s-2z-sz+\sqrt{4sz+(s(-1+z)+2z)^2} \right)^2, \left( 4+2\sqrt{s^2-2s^2z+(2+s)^2z^2}+s^2(-1+z)(-1+zm)+4z(-1+zm)- \right.$$

$$\left. s(4-4z+\sqrt{s^2-2s^2z+(2+s)^2z^2})(-1+zm)-2\left( 2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)zm+ \right.$$

$$\left. \sqrt{2}\sqrt{\left( \left( s^2(-1+z)^2+2\left( 1+2z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)z^2-z\left( 2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right) \right) + s\left( 2+4z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right)z^2- \right.$$

$$\left. \left. z\left( 4+\sqrt{s^2-2s^2z+(2+s)^2z^2} \right) \right) \left( s^2-2s^2zm+(2+s)^2zm^2 \right) \right) \Big/ \left( 2+s-2z-sz+\sqrt{4sz+(s(-1+z)+2z)^2} \right)^2 \Big\}$$

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$$2(2+\sqrt{s^2-2s^2z+(2+s)^2z^2})zm-\sqrt{2}\sqrt{\left(\left(s^2(-1+z)^2+2(1+2z+\sqrt{s^2-2s^2z+(2+s)^2z^2})-z(2+\sqrt{s^2-2s^2z+(2+s)^2z^2})\right)+ \right.$$

$$\left. s(2+4z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2})-z(4+\sqrt{s^2-2s^2z+(2+s)^2z^2})\right)\left(s^2-2s^2zm+(2+s)^2zm^2\right)\Bigg/$$

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$$\left. z(4+\sqrt{s^2-2s^2z+(2+s)^2z^2})\right)\left(s^2-2s^2zm+(2+s)^2zm^2\right)\Bigg/ \left(2+s-2z-sz+\sqrt{4sz+(s(-1+z)+2z)^2}\right)^2 \Big\}$$

→ All eigenvalues  $\rho_i$  such that  $|\rho_i| \leq 1$  when  $z_m > z$

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$$\left. s\left(2+4z^2+\sqrt{s^2-2s^2z+(2+s)^2z^2}\right)z-\left(4+\sqrt{s^2-2s^2z+(2+s)^2z^2}\right)\right)\left(s^2-2s^2zm+(2+s)^2zm^2\right)\Bigg/\left. \right.$$

$$\left(2+s-2z-sz+\sqrt{4sz+(s(-1+z)+2z)^2}\right)^2, \left(4+2\sqrt{s^2-2s^2z+(2+s)^2z^2}+s^2(-1+z)(-1+zm)+4z(-1+zm)- \right.$$

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$$\left. \left. z\left(4+\sqrt{s^2-2s^2z+(2+s)^2z^2}\right)\right)\left(s^2-2s^2zm+(2+s)^2zm^2\right)\Bigg/\left(2+s-2z-sz+\sqrt{4sz+(s(-1+z)+2z)^2}\right)^2\right\}$$

→ All eigenvalues  $\rho_i$  such that  $|\rho_i| \leq 1$  when  $z_m > z$

Reduced emigration probabilities are favored.



## A few take-home messages

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- ▶ Kin competition favors the evolution of emigration
- ▶ Spatial heterogeneity only does not...  
but dispersal can evolve when local conditions change with time and space.
- ▶ Dispersal is a complicated trait to study, because it affects spatial structure (→ Lecture 4).

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# Appendix

More on  $q$

Stability analysis



## More on $q$

### New parameters:

$n$  Number of demes

$\mu$  Mutation probability (infinite allele model)

[Cockerham and Weir, 1987]

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$m = \frac{1 - z}{1 - cz}$  Backward dispersal probability

[Cockerham and Weir, 1987]

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### Probability that two individuals came from the same deme and

- ▶ are in the same deme:  $a = (1 - m)^2 + \frac{m^2}{n-1}$ ,

[Cockerham and Weir, 1987]

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[Cockerham and Weir, 1987]

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### Probabilities of identity by descent, with replacement:

▶ In the same deme:  $q_{0,t+1} = \frac{1}{N} + \frac{N-1}{N}(1-\mu)^2 (a q_{0,t} + (1-a) q_{1,t})$ ,

[Cockerham and Weir, 1987]

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- ▶ In different demes:  $q_{1,t+1} = (1-\mu)^2 (b q_{0,t} + (1-b) q_{1,t})$ ,

[Cockerham and Weir, 1987]

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## More on $q$ (2)

$$q_{0,t+1} = \frac{1}{N} + \frac{N-1}{N}(1-\mu)^2 (a q_{0,t} + (1-a) q_{1,t}),$$

$$q_{1,t+1} = (1-\mu)^2 (b q_{0,t} + (1-b) q_{1,t}),$$

## Order of limits

[Cockerham and Weir, 1987]

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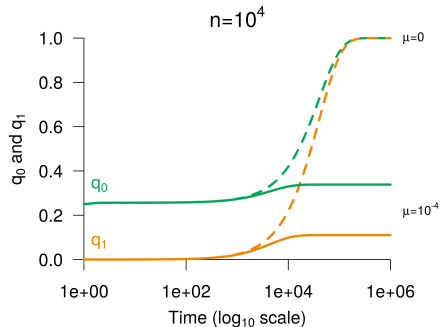
## More on $q$ (2)

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### Order of limits

- ▶ When  $\mu = 0$ ,  
 $q_{0,\infty} = q_{1,\infty} = 1$ .



[Cockerham and Weir, 1987]

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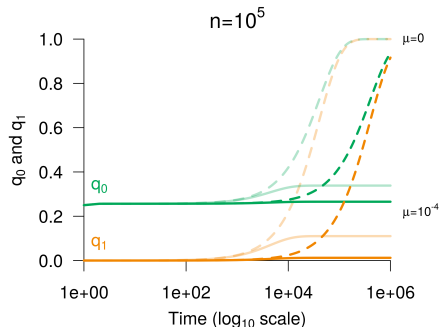


## More on $q$ (2)

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$$q_{1,t+1} = (1-\mu)^2 (b q_{0,t} + (1-b) q_{1,t}),$$

### Order of limits

- ▶ When  $\mu = 0$ ,  
 $q_{0,\infty} = q_{1,\infty} = 1$ .
- ▶ When  $n \rightarrow \infty$ ,  $q_{1,\infty} = 0$   
and  $q_{0,\infty} =$   
 $\frac{1}{N} + \frac{N-1}{N}(1-\mu)^2 (a q_{0,\infty})$ .



[Cockerham and Weir, 1987]

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# Outline

More on  $q$

Stability analysis

# Stability analysis for discrete-time models

## Model

$$N_1(t+1) = G_1(N_1(t), N_2(t), \dots, N_k(t))$$

$$N_2(t+1) = G_2(N_1(t), N_2(t), \dots, N_k(t))$$

⋮

$$N_k(t+1) = G_k(N_1(t), N_2(t), \dots, N_k(t))$$

# Stability analysis for discrete-time models

## Model

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$$\vdots$$

$$N_k(t+1) = G_k(N_1(t), N_2(t), \dots, N_k(t))$$

## Equilibrium

$\tilde{\mathbf{N}} = (\tilde{N}_1, \dots, \tilde{N}_k)$ , such that

$$G_1(\tilde{N}_1, \dots, \tilde{N}_k) = \tilde{N}_1$$

$$\vdots$$

$$G_k(\tilde{N}_1, \dots, \tilde{N}_k) = \tilde{N}_k$$

# Stability analysis for discrete-time models

- 2 Write system of equations for the change over time of a small derivation from the equilibrium

## Deviations from equilibrium

Define  $n_i(t) = N_i(t) - \tilde{N}_i$ .

## Stability analysis for discrete-time models

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### Deviations from equilibrium

Define  $n_i(t) = N_i(t) - \tilde{N}_i$ .

$$n_i(t+1) = G_i(N_1(t), \dots, N_k(t)) - \tilde{N}_i$$

## Stability analysis for discrete-time models

- Write system of equations for the change over time of a small derivation from the equilibrium, and get a linear approximation of this system (Taylor series)

### Deviations from equilibrium

Define  $n_i(t) = N_i(t) - \tilde{N}_i$ .

$$\begin{aligned}n_i(t+1) &= G_i(N_1(t), \dots, N_k(t)) - \tilde{N}_i \\ &\approx 0 + \left. \frac{\partial G_i}{\partial N_1} \right|_{\mathbf{N}(t)=\tilde{\mathbf{N}}} (N_1(t) - \tilde{N}_1) + \dots + \left. \frac{\partial G_i}{\partial N_k} \right|_{\mathbf{N}(t)=\tilde{\mathbf{N}}} (N_k(t) - \tilde{N}_k).\end{aligned}$$

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In matrix form:

$$\begin{pmatrix} n_1 \\ \vdots \\ n_k \end{pmatrix} (t+1) = \left( \begin{array}{ccc} \left. \frac{\partial G_1}{\partial N_1} & \dots & \frac{\partial G_1}{\partial N_k} \right|_{\mathbf{N}=\tilde{\mathbf{N}}} \\ \vdots & \dots & \vdots \\ \left. \frac{\partial G_k}{\partial N_1} & \dots & \frac{\partial G_k}{\partial N_k} \right|_{\mathbf{N}=\tilde{\mathbf{N}}} \end{array} \right) \cdot \begin{pmatrix} n_1 \\ \vdots \\ n_k \end{pmatrix} (t)$$



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In matrix form:

$$\underbrace{\begin{pmatrix} n_1 \\ \vdots \\ n_k \end{pmatrix}}_{\mathbf{n}(t+1)} (t+1) = \underbrace{\left( \begin{array}{ccc|c} \frac{\partial G_1}{\partial N_1} & \cdots & \frac{\partial G_1}{\partial N_k} & \\ \vdots & \cdots & \vdots & \\ \frac{\partial G_k}{\partial N_1} & \cdots & \frac{\partial G_k}{\partial N_k} & \end{array} \right)}_{\mathbf{J}} \Big|_{\mathbf{N}=\tilde{\mathbf{N}}} \cdot \underbrace{\begin{pmatrix} n_1 \\ \vdots \\ n_k \end{pmatrix}}_{\mathbf{n}(t)} (t)$$

## Stability analysis for discrete-time models (3)

- 3 Identify solutions of  $\mathbf{n}(t + 1) = \mathbf{J} \cdot \mathbf{n}(t)$

[Case, 2000]

## Stability analysis for discrete-time models (3)

- 3 Identify solutions of  $\mathbf{n}(t + 1) = \mathbf{J} \cdot \mathbf{n}(t)$

Solution:

$$\mathbf{n}(t) = c_1 \boldsymbol{\nu}_1 \lambda_1^t + c_2 \boldsymbol{\nu}_2 \lambda_2^t + \dots + c_k \boldsymbol{\nu}_k \lambda_k^t,$$

with the  $c_i$  constants determined by the initial conditions, and  $\boldsymbol{\nu}_{(i)}$  an eigenvector associated to the eigenvalue  $\lambda_i$ , i.e.,  $\mathbf{J} \cdot \boldsymbol{\nu}_{(i)} = \lambda_i \boldsymbol{\nu}_{(i)}$ .

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**Leading eigenvalue:** eigenvalue with the largest modulus

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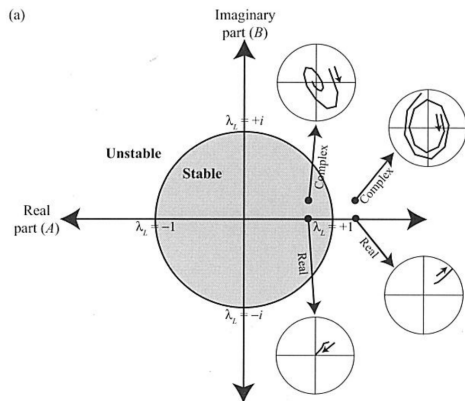
**Modulus:** for a complex number  $\lambda = A + \imath B$ ,

$$|\lambda| = \sqrt{A^2 + B^2}.$$

[Case, 2000]

# Stability analysis for discrete-time models (4)

## 4 Inspect the eigenvalues of $\mathbf{J}$



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